

## Lesson 17:

Let us continue with our study of the section 4.2

Let  $V$  and  $W$  be vector spaces and  $T:V \rightarrow W$  a linear transformation.

Recall that Kernel of  $T$ , denoted by  $\text{Ker}T = \{v \in V: T(v)=0\}$

Note that if  $T:R^n \rightarrow R^m$  is a linear transformation and  $A$  is a standard matrix of this linear transformation, then  $\text{Ker}T = \text{Nul}A$

Facts about  $\text{Ker}T$ .

1. Let  $V$  and  $W$  be vector spaces and  $T:V \rightarrow W$  a linear transformation, then  $\text{Ker}T$  is a subspace of  $V$ .

Proof:

i)  $0 \in \text{Ker}T$  because  $T(0)=0$  by the definition of  $\text{Ker}T$ .

ii)  $u, v \in \text{Ker}T \Rightarrow T(u)=T(v)=0 \Rightarrow T(u+v)=T(u)+T(v)=0+0=0 \Rightarrow u+v \in \text{Ker}T$

iii) For any real number  $\alpha$  and any  $u \in \text{Ker}T \Rightarrow T(\alpha u)=\alpha T(u)=\alpha 0=0 \Rightarrow \alpha u \in \text{Ker}T$ .

therefore all the requirements for being a subspace are satisfied and  $\text{Ker}T$  is a subspace of  $V$ .

2. Let  $V$  and  $W$  be vector spaces and  $T:V \rightarrow W$  a linear transformation.  $T$  is one-one  $\Leftrightarrow \text{Ker}T = \{0\}$

Proof:

$\Rightarrow$

Given that  $T$  is one-one (that is  $T(u)=T(v) \rightarrow u=v$ )

$$u \in \text{Ker}T \rightarrow T(u)=0$$

since  $T(0)=0$

we have  $T(u)=T(0)$ . Since  $T$  is one-one,  $u=0$ .

therefore

$$u \in \text{Ker}T \rightarrow u=0$$

which means  $\text{Ker}T=\{0\}$

←

Now we are assuming that  $\text{Ker}T=\{0\}$  and have to show that  
Given that  $T$  is one-one (that is  $T(u)=T(v) \rightarrow u=v$ )

$T(u)=T(v) \rightarrow T(u)-T(v)=0 \rightarrow T(u-v)=0 \rightarrow u-v \in \text{Ker}T$   
( $T(u)-T(v)=T(u-v)$  because  $T$  is a linear transformation.)  
Since  $\text{Ker}T=\{0\}$  and  $u-v \in \text{Ker}T$ ,  $u-v=0$  or  $u=v$ .

Therefore, we have shown that  
 $T(u)=T(v) \rightarrow u=v$ .

Which means that  $T$  is one-one.

QED

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Recall the definition of the range of a map on the page 232 in third edition or page 227 of the second updated edition.

Note the following property of the range as stated in the problem #30 on the page 235 of the third edition.

Let  $V$  and  $W$  be vector spaces and  $T:V \rightarrow W$  a linear transformation, then Range of  $T$  is a subspace of  $W$ .

Proof:

a)  $0 \in \text{Range of } T$  because  $T(0)=0$  for  $0$  in  $V$ .

b) if  $p, q$  are in Range of  $T$ , we can find  $u$  and  $v$  in  $V$  such that  $T(u)=p$  and  $T(v)=q$ .

$u+v \in V$ , therefore  $T(u+v)=T(u)+T(v)=p+q$  is in the Range of  $T$ .

c) Take a real number  $c$  and a vector  $w$  in the Range of  $T$ . We can find  $x$  in  $V$  such that  $T(x)=w$ .

$cx \in V$ , therefore  $T(cx)=cT(x)=cw$  is in the Range of  $T$ .

Therefore Range of  $T$  is a subspace of  $W$ .

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### Example 18.1

Let us take up #32 on page 235 in third edition.

$T:P_2 \rightarrow R^2$  is defined by  $T(p)=\begin{bmatrix} p(0) \\ p(0) \end{bmatrix}$

We have to find

a) polynomials  $p_1$  and  $p_2$  in  $P_2$  such that  $\text{Ker}T=\text{Span}\{p_1, p_2\}$

b) description of the Range of  $T$ .

a)

Consider  $p=a+bx+cx^2 \in P_2$

$p=a+bx+cx^2 \in \text{Ker}T \rightarrow p(0)=0 \rightarrow a=0$

therefore an element of  $\text{Ker}T$  is of the form  $bx+cx^2$  and

$$\text{Ker } T = \text{span}\{x, x^2\}$$

b)

$$p = a + bx + cx^2 \in P_2$$

$$\Rightarrow T(p) = \begin{bmatrix} a \\ a \end{bmatrix} \in \text{range of } T.$$

Note that for any real number  $a$ ,  $\begin{bmatrix} a \\ a \end{bmatrix} \in \text{range of } T.$

Therefore Range of  $T = \text{span}\left\{\begin{bmatrix} 1 \\ 1 \end{bmatrix}\right\}.$

Example 18.2:

Look at #34 in the third edition.

We are given a map  $T: C[0,1] \rightarrow C[0,1]$

defined by  $T(f) =$  the antiderivative of  $F$  of  $f$  such that  $F(0) = 0$

a) we have to show that  $T$  is a linear transformation.

b) we have to describe  $\text{Ker } T.$

( Let us first see some examples of how does this map work.

Note that  $f(x) = x^2 + x \in C[0,1]$  and  $F = \int (x^2 + x) dx = \frac{x^3}{3} + \frac{x^2}{2} + C$  where  $C$  is an arbitrary constant.

according to the above definition  $T(f) = \frac{x^3}{3} + \frac{x^2}{2}$

whereas for  $f(x) = \sin x$ , note that  $\int f(x) dx = -\cos(x) + C$ ,  $F(x) = -\cos(x) + 1$

a) consider  $f, g$  in  $C[0,1]$

$$T(f) = F$$

$$T(g) = G$$

$$F(0) = 0$$

$$G(0)=0$$

therefore

$$(F+G)(0)=F(0)+G(0)=0+0=0$$

also for any real number  $\alpha$ ,  $\alpha F(0)=0$

and

$$T(f+g)=F+G=T(f)+T(g)$$

$$T(\alpha f)=\alpha F$$

therefore  $T$  is a linear transformation.

b)

$f \in \text{Ker}T \rightarrow$  the antiderivative  $F$  such that  $F(0)=0$  will have to be the zero function.

Note that the zero function ( a function with 0 as the only value) is a constant function.

Therefore the only possible definition of  $f$  is  $f(x)=0$  for all  $x$ .

Or informally  $f=0$

and  $\text{Ker}T=\{0\}$

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please finish all the practice problems in the section 4.2.