

Lesson 17:

Let us continue with our study of the section 4.2

Let V and W be vector spaces and $T:V \rightarrow W$ a linear transformation.

Recall that Kernel of T , denoted by $\text{Ker}T = \{v \in V: T(v)=0\}$

Note that if $T:R^n \rightarrow R^m$ is a linear transformation and A is a standard matrix of this linear transformation, then $\text{Ker}T = \text{Nul}A$

Facts about $\text{Ker}T$.

1. Let V and W be vector spaces and $T:V \rightarrow W$ a linear transformation, then $\text{Ker}T$ is a subspace of V .

Proof:

i) $0 \in \text{Ker}T$ because $T(0)=0$ by the definition of $\text{Ker}T$.

ii) $u, v \in \text{Ker}T \Rightarrow T(u)=T(v)=0 \Rightarrow T(u+v)=T(u)+T(v)=0+0=0 \Rightarrow u+v \in \text{Ker}T$

iii) For any real number α and any $u \in \text{Ker}T \Rightarrow T(\alpha u)=\alpha T(u)=\alpha 0=0 \Rightarrow \alpha u \in \text{Ker}T$.

therefore all the requirements for being a subspace are satisfied and $\text{Ker}T$ is a subspace of V .

2. Let V and W be vector spaces and $T:V \rightarrow W$ a linear transformation. T is one-one $\Leftrightarrow \text{Ker}T = \{0\}$

Proof:

\Rightarrow

Given that T is one-one (that is $T(u)=T(v) \rightarrow u=v$)

$$u \in \text{Ker}T \rightarrow T(u)=0$$

since $T(0)=0$

we have $T(u)=T(0)$. Since T is one-one, $u=0$.

therefore

$$u \in \text{Ker}T \rightarrow u=0$$

which means $\text{Ker}T=\{0\}$

←

Now we are assuming that $\text{Ker}T=\{0\}$ and have to show that
Given that T is one-one (that is $T(u)=T(v) \rightarrow u=v$)

$T(u)=T(v) \rightarrow T(u)-T(v)=0 \rightarrow T(u-v)=0 \rightarrow u-v \in \text{Ker}T$
($T(u)-T(v)=T(u-v)$ because T is a linear transformation.)
Since $\text{Ker}T=\{0\}$ and $u-v \in \text{Ker}T$, $u-v=0$ or $u=v$.

Therefore, we have shown that
 $T(u)=T(v) \rightarrow u=v$.

Which means that T is one-one.

QED

Recall the definition of the range of a map on the page 232 in third edition or page 227 of the second updated edition.

Note the following property of the range as stated in the problem #30 on the page 235 of the third edition.

Let V and W be vector spaces and $T:V \rightarrow W$ a linear transformation, then Range of T is a subspace of W .

Proof:

a) $0 \in \text{Range of } T$ because $T(0)=0$ for 0 in V .

b) if p, q are in Range of T , we can find u and v in V such that $T(u)=p$ and $T(v)=q$.

$u+v \in V$, therefore $T(u+v)=T(u)+T(v)=p+q$ is in the Range of T .

c) Take a real number c and a vector w in the Range of T . We can find x in V such that $T(x)=w$.

$cx \in V$, therefore $T(cx)=cT(x)=cw$ is in the Range of T .

Therefore Range of T is a subspace of W .

Example 18.1

Let us take up #32 on page 235 in third edition.

$T:P_2 \rightarrow R^2$ is defined by $T(p)=\begin{bmatrix} p(0) \\ p(0) \end{bmatrix}$

We have to find

a) polynomials p_1 and p_2 in P_2 such that $\text{Ker}T=\text{Span}\{p_1, p_2\}$

b) description of the Range of T .

a)

Consider $p=a+bx+cx^2 \in P_2$

$p=a+bx+cx^2 \in \text{Ker}T \rightarrow p(0)=0 \rightarrow a=0$

therefore an element of $\text{Ker}T$ is of the form $bx+cx^2$ and

$$\text{Ker } T = \text{span}\{x, x^2\}$$

b)

$$p = a + bx + cx^2 \in P_2$$

$$\Rightarrow T(p) = \begin{bmatrix} a \\ a \end{bmatrix} \in \text{range of } T.$$

Note that for any real number a , $\begin{bmatrix} a \\ a \end{bmatrix} \in \text{range of } T.$

Therefore Range of $T = \text{span}\left\{\begin{bmatrix} 1 \\ 1 \end{bmatrix}\right\}.$

Example 18.2:

Look at #34 in the third edition.

We are given a map $T: C[0,1] \rightarrow C[0,1]$

defined by $T(f) =$ the antiderivative of F of f such that $F(0) = 0$

a) we have to show that T is a linear transformation.

b) we have to describe $\text{Ker } T.$

(Let us first see some examples of how does this map work.

Note that $f(x) = x^2 + x \in C[0,1]$ and $F = \int (x^2 + x) dx = \frac{x^3}{3} + \frac{x^2}{2} + C$ where C is an arbitrary constant.

according to the above definition $T(f) = \frac{x^3}{3} + \frac{x^2}{2}$

whereas for $f(x) = \sin x$, note that $\int f(x) dx = -\cos(x) + C$, $F(x) = -\cos(x) + 1$

a) consider f, g in $C[0,1]$

$$T(f) = F$$

$$T(g) = G$$

$$F(0) = 0$$

$$G(0)=0$$

therefore

$$(F+G)(0)=F(0)+G(0)=0+0=0$$

also for any real number α , $\alpha F(0)=0$

and

$$T(f+g)=F+G=T(f)+T(g)$$

$$T(\alpha f)=\alpha F$$

therefore T is a linear transformation.

b)

$f \in \text{Ker}T \rightarrow$ the antiderivative F such that $F(0)=0$ will have to be the zero function.

Note that the zero function (a function with 0 as the only value) is a constant function.

Therefore the only possible definition of f is $f(x)=0$ for all x .

Or informally $f=0$

and $\text{Ker}T=\{0\}$

please finish all the practice problems in the section 4.2.